KLAY-INSTRUMENTS

INSTRUCTION MANUAL

"Intelligent" Pressure and level transmitters

SERIES 4000 and 4000-SAN

PROFIBUS PA

PROFI PROCESS FIELD BUS
PA PROFILE V 3.02

• Warning •

Read the recommendations and warnings in this manual before the instrument is installed. For personal safety, optimal use and maintenance of the Series 4000 and 4000 SAN, these instructions should be studied carefully.

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1. INTRODUCTION

The Series 4000 and Series 4000-SAN are solid-state pressure- and level transmitters based upon a piezoresistive silicon sensor, with a very high burst pressure. The sensor element is mounted in a stainless steel foot. A strong stainless steel "flush" diaphragm protects the sensor from the process medium. A very small amount of special oil fills the chamber surrounding the sensor and transfers pressure from the flush mounted diaphragm to the sensor.

Pressure on the sensor element creates a very small deflection of the silicon substrate and bridge network. The resulting strain in the silicon resistors causes a change in the bridge resistance that is proportional to the pressure applied. The transmitter electronics detects this change in bridge resistance and converts it into a measuring value. The amplifier system is based on a single Integrated Circuit, which ensures a perfect linearity in the output, all within an accuracy of 0.075 %. Together with the **Klay flush diaphragm technology** the long term stability is perfect.

1.1 DESCRIPTION SERIES 4000-SAN

The SERIES 4000-SAN are specially designed with a flush mounted diaphragm so they fully meet the needs of the food, pharma and chemical industries. Standard the wetted parts are made of SS 316, other materials are available, like Hastelloy C. Various process connections can be delivered, such as Tri-Clamp (1,5”, 2” and 3”), SMS (1,5” and 2”), dairy milk couplings (DN 25, 40 and 50), flanges (DIN and ANSI) and sanitary weld-on nipples (ø 48, 62 and 85 mm.)

1.2 DESCRIPTION SERIES 4000

The SERIES 4000 are specially designed for the pulp- and paper or similar industries, where clogging is a problem. The very compact construction of the SERIES 4000 permits flush installation with the tank- or pipe wall. Standard the wetted parts are made of SS 316, a lot of other materials like Hastelloy C and Gold plated are available as an option.

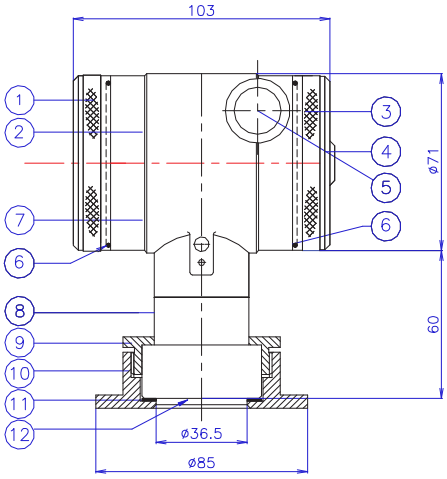
All transmitters are **fully temperature compensated**, which means that various process temperatures have nearly no effect on the accuracy of the output signal. When a failure occurs, the transmitter is repairable. However, for optimum accuracy the transmitter has to be send back to the factory.

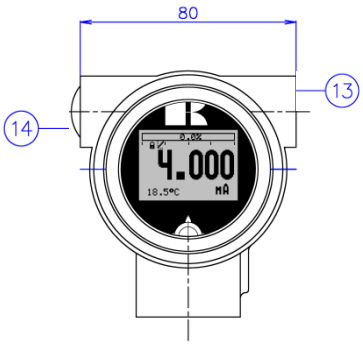
1.3 BAROMETRIC REFERENCE

The series 4000 is in basic a so-called "relative transmitter" which means that barometric changes will not affect the zero. The venting is placed in the cover of the electronic housing and is the filter for the barometric reference to atmospheric pressure. The venting must be kept clean.

2. DIMENSIONAL DRAWINGS

Series 4000-SAN



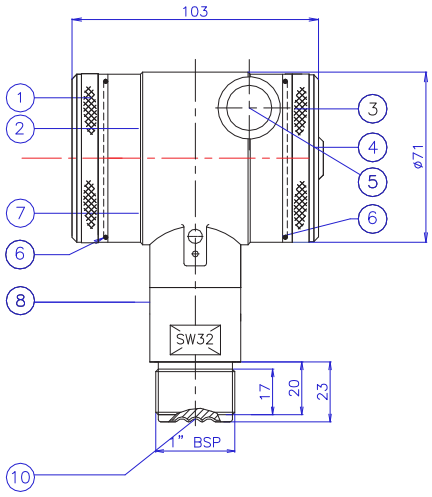


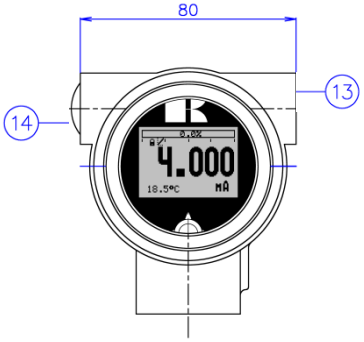
Front view: Transparant cover, option "I" (extra price)

	Description	Material
①	Cover	SS 304
②	Display with navigation button	
③	Cover with venting	SS 304
④	Venting	PA
⑤	M20 x 1,5 cable entry (without gland) *	
⑥	O-Ring	EPDM
⑦	Electronic housing	SS 304

	Description	Material
⑧	Foot	SS 316
⑨	Lock ring	SS 304
⑩	Weld-on nipple	SS 316 L
⑪	Gasket	PTFE
⑫	Diaphragm	SS 316 L
⑬	M20 x 1.5 cable entry (without gland) *	
⑭	M20 x 1.5 cable entry (Blanking plug)	PE

Series 4000 - 1" BSP





Front view: Transparent cover, option "I" (extra price)

	Description	Material
①	Cover	SS 304
②	Display with navigation button	
③	Cover with venting	SS 304
④	Venting	PA
⑤	M20 x 1,5 cable entry (without gland) *	
⑥	O-Ring	EPDM
⑦	Electronic housing	SS 304

	Description	Material
⑧	Foot	SS 316
⑨	Lock ring	SS 304
⑩	Diaphragm	SS 316 L
⑬	M20 x 1.5 cable entry (without gland) *	
⑭	M20 x 1.5 cable entry (Blanking plug)	PE

** As standard the Series 4000 will be supplied with **two** cable entries M20 x 1,5. A cable gland can be supplied by request (extra costs).*

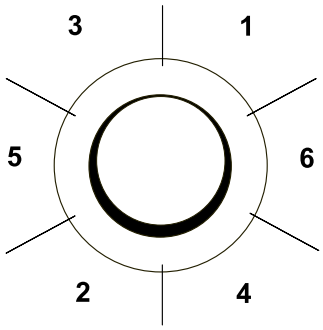
3. INSTALLING THE TRANSMITTER

The diaphragm of the transmitter is protected with a special protection cap. Protect the diaphragm until installation takes place. **Do not damage the diaphragm.**

3.1 INSTALLING WELD-ON NIPPLE

A certified welder should perform the installation of the weld-on nipple.
Weld with Argon, MIG or TIG, with the smallest welding pin possible.

1. Cut a hole in the process vessel or pipe for a precise fit of the weld-on nipple. The hole should be a tight fit when coupled with the weld-on nipple.
2. Prepare the hole by bevelling the edge to accept filler material.
3. Remove the weld-on nipple from the transmitter.
   Remove the gasket and O-Ring out of the weld-on nipple!



WARNING
Improper installation may result in distortion of the weld-on nipple. Excessive heat will distort the weld-on nipple. Weld in sections as shown in the figure left. Allow adequate cooling between passes. To reduce the chances of distortion to the weld-on nipple, use a mandrel.

SERIES 4000-SAN:	Part.no. 1019 – Art.no. 10230
	Lockring Part.no. 1160 – Art.no. 10001
SERIES 4000:	Part.no. 1016 – Art.no. 10282

Determine (before welding) the position of the electronic housing, so that the cable entry and the venting are in the right position. After welding these positions are fixed.

4. Position the weld-on nipple in the vessel hole and tack six places. The weld sequence is shown in the figure above.
5. Weld the weld-on nipple in place using 0,03 to 0,045 in. (0,762 to 1,143 mm) stainless rod as filler material in the bevelled area. Adjust amperage for penetration.
6. Remove the mandrel after the welding operation.

3.2 INSTALLING TRANSMITTER SERIES 4000-SAN (Code W)

1. Make sure to correctly locate the packing within the weld-on nipple.
2. Improper installation of the packing can cause a process leak.
3. Position the transmitter into the weld-on nipple and begin engaging threads.
4. The transmitter can be rotated prior to seating enabling the user to optimize access to calibration adjustments, cable entry, and local indicator.
5. Once the Lock ring has been hand tightened, it must be tightened with an additional turn (± 1/8") with adjustable pliers.

3.3 INSTALLING TRANSMITTER SERIES 4000 (Code W33)

1. After welding, clean up edges, and take care of the inside nipple wall.
2. Make sure the O-rings ⑩ and ⑪ are properly located.
3. Improper installation of the O-ring can cause a process leak.
4. Apply silicone grease to the O-ring ⑩, diaphragm ring and the hole inside wall of the weld-on nipple, this prevents galvanic cell corrosion between transmitter and the nipple inside.
5. Install the transmitter and fix it with the SS M8 bolt.

3.4 MOUNTING POSITION

When the transmitter is mounted horizontally, the cable gland must be pointed downwards.

3.5 MOUNTING POSITION EFFECT

All transmitters are calibrated in vertical position (diaphragm points downwards). If the transmitter is mounted in another position, there can be a little zero shift. After installation of the transmitter the zero must be set to 0,000 with **P103** cancel mounting position effect. This will not affect the span.

3.6 CALIBRATION

All transmitters are fully calibrated at the factory, to customer specified range. If the calibration is not specified, the transmitter will be calibrated at the maximum span.

3.7 PROFIBUS PA CABLE

Under the cover ③ you will find the terminal board. Special PROFIBUS® cable must be used for proper communication. For further detailed description of cable selection, see "*Guidelines for planning and commissioning PROFIBUS DP/PA*" and "*PROFIBUS PA User and Installation Guideline*" both on www.profibus.com and IEC 61158-2 on www.iec.ch.

Shielded Profibus cable

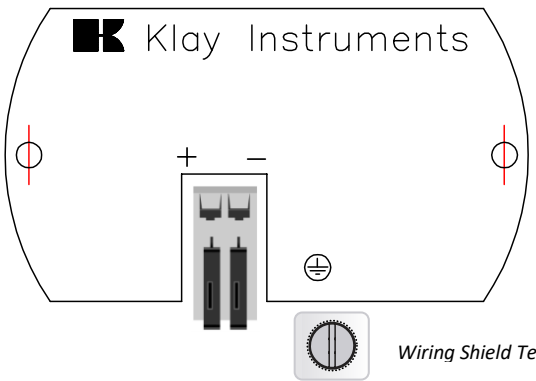
The PROFIBUS® standard defines two variations of bus cable: Type A and Type B. However it is recommended to use cable Type A in all new installations. Type A is recommended for high transmission speeds and permits a doubling of the network distance in comparison to Type B.

Type A Technical specification:

- **Impedance**: 35 up to 165 Ohm at frequencies from 3 to 20 Mhz.
- **Cable capacity**: < 30 pF per meter.
- **Core diameter**: > 0,34 mm², corresponds to AWG 22.
- **Cable type**: Twisted pair cable. 1x2 or 2x2 or 1x4 lines.
- **Resistance**: < 110 Ohm per km.
- **Signal damping**: max. 9 dB over total length of line section.
- **Shielding**: CU shielding braid or shielding braid and shielding foil.
- **Max. Bus length**: 200 m at 1500 kbit/s, up to 1,2 km at 93,75 kbit/s. (Extendable by repeaters)

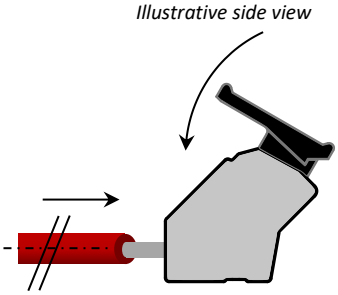
Using other types of cable will result in incorrect and disrupted transmissions in the PROFIBUS® network and is strongly discouraged. Do not run wiring in open trays with power wiring, or near heavy electrical equipment (for example frequency controllers or heavy pumps). To eliminate electromagnetic effects it is highly recommended to us a EMC Cable gland. (Option G73)

3.8 CONNECTION TERMINAL



Wiring Shield Terminal

Illustrative side view



Insert the wires into the connector and push the lever down by hand.

The figure on page 6 shows the wiring connection of the transmitter. The 2-wires must be connected to the terminal board. The polarity of the Series 4000-PROFIBUS PA is independent and reversing the polarity will not affect the functionality or damage the transmitter. The transmitter automatically detects the polarity of the connected Profibus® cable.

The wiring terminals can be operated without a screwdriver. The opening levers of the terminals can be lifted and pressed down by hand. Lift the opening levers of the terminals and insert the corresponding wires. Press down the levers by hand, the terminal spring will close and the wire is clamped.

3.9 GROUNDING

The transmitter must always be connected to ground. In case the process connection is already connected to ground (for example by the tank or pipe line), do not connect the instrument to ground.

3.10 CABLE SHIELDING

The cable shield must only be connected at **one** side. Optionally an EMC Cable gland can be provided (Option G73). When a EMC Cable gland is used, the cable shield at the Profibus power supply or installation must be disconnected.

⚠ **Please ensure that the instrument is not connected to ground twice. For correct grounding the recommendations of IEC 61158-2 must be followed.**

3.11 TERMINATION

Termination of the bus prevents signal reflections on the PROFIBUS® cable. A terminator is a combination of a resistor and a capacitor. Wrong or missing termination results in transmission errors. At the end of each cable trunk a terminator must be used. In common a terminator is integrated in a segment coupler. When there is no integrated terminator present in the trunk, a separate terminator must be used.

4. REMAINING

4.1 CE / EMC-RULES

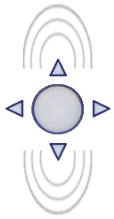
All Klay transmitters are manufactured in accordance with the RFI / EMC directives and comply with the CE standard. All transmitters are fitted with RFI filters, which provide optimum, trouble-free operation. Our products are in conformity with EMC-Directive 2014/30/EU based on test results using harmonized standards.

4.2 TRACEBILITY / YEAR OF MANUFACTURING

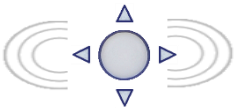
The year of manufacturing of the transmitter can be traced as follows: take the first three numbers from the serial number that is engraved in the transmitter and add 1600 to it.
Example: Serial Number 41602123. The year of manufacturing is 1600 + 416 = 2016.

5. GRAPHIC DISPLAY AND NAVIGATION BUTTON

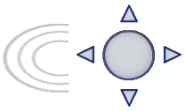
The Series 4000 has a multifunctional display where different values can be displayed simultaneously. The display is equipped with a backlight. The entire menu is controlled by a navigation button. The navigation button has the following possibilities of movement: up, down, left, and right. The navigation button needs to be pushed when conformation or saving is needed.



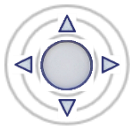
Move the navigation button up or down to browse through various menus. These movements can be distinct in choices of: program points, navigation through menu's and increase or decrease measurement value's.



Move the navigation button left or right to navigate horizontally through the menu or positions on the display.



It is always possible to return to the previous menu. Move the navigation button to the left to return to the previous menu.

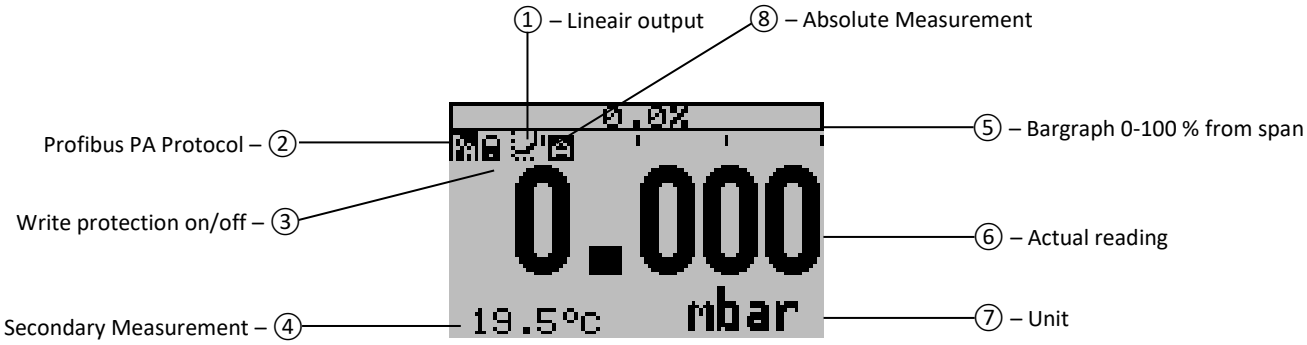


By pushing the navigation button each choice will be **confirmed** or a setting will be **saved**.

Figure 1. Display Series 4000, fully rotatable (360˚)

5.1 GRAPHIC DISPLAY READOUT

When the transmitter is powered, a startup screen with the name of the transmitter (Series 4000) and the software version appear for a few seconds. The **PROFIBUS® address** is shown at the bottom of the display. As standard (Unconfigured) the address is **126**. This address is used for configuration and commissioning purposes only. The address can be changed with Program point P113 or a Profibus Master device (Only Class 2).



EXPLANATION OF SYMBOLS:

1. – Linear output: Displays when any form of linearization is applied. a Straight line means no linearization is applied. When a linearization is applied a curve will be displayed.
2. – Profibus PA: Profibus PA Protocol applied
3. – Write protection on/off: Displays if protection against adjustments and configuration is on or off
4. – Secondary Measurement: Displays a secondary chosen measurement.
5. – Bargraph 0 - 100 % from span: Displays the percentage of the measured span.
6. – Measurement: Displays the actual reading, temperature or percentage
7. – Unit: Displays the selected unit.
8. – Absolute: Appears when the measurement is in absolute range.

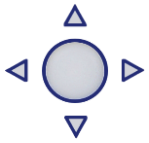
5.2 SUMMARY PROGRAMMING POINTS

PROGRAM POINT	NAME	FUNCTION
P100	Menu-Exit menu	Start and exit
P101	ZERO value	Zero adjustment (ZERO 0%) with or without test pressure
P102	SPAN value	Span adjustment (SPAN 100 %) with or without test pressure
P103	MOUNT correction	Cancel mounting position effect
P104	UNITS	Selection of engineering unit to be displayed
P105	REVERSE Out	Scaling 0 - 100 % or 100 - 0 %
P106	DAMPING	Adjustable damping (0,00 till 25,00 s)
P107	LANGUAGE	Language choice between: English, Dutch, German, Russian, Polish and French.
P108	DEVICE SETUP	Configuration: Protection, Backlight, Temp Units, Temp min/max Value Secondary value and PA_OUTSCALE
P109	READOUT	Readout options on display: Unit, percentage and Sensor temperature
P110	TANK LINEARIZATION	Configuration for tank linearization
P111	INFORMATION	Contact information of Klay Instruments, made settings, and software revision
P112	CALIBRATE	Only available for the manufacturer
P113	PA Address	Selection of PA Address 2 to 126 (Factory setting 126)
P114	FACTORY	Only available for the manufacturer

⚠ **Configuring the transmitter local and remote simultaneously will cause transmission errors and must be prevented.**

6. EXPLANATION PROGRAMMING POINTS

6.1 ZERO ADJUSTMENT



The transmitter is set to 0 mbar at atmospheric pressure.
The **ZERO** can be adjusted at a lower or higher point. This will be explained step by step by an example.

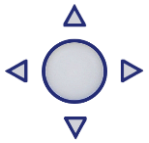
Example: Increase ZERO till 100 mbar.

1. The measuring unit of the transmitter is set to mbar. If not this can be selected by choosing the right measuring unit in program point **P104 – UNITS (paragraph 6.4)**
2. Navigate to program point **P101 - ZERO Value**, and push the navigation button to enter the menu.
3. Two choices appear on the screen: **set manual** and **use process**
   Set manual = Configuration without test pressure.
   Use process = Configuration with applied pressure.
4. Choose **set manual**, +000.0 (mbar) will appear on the display.
5. Increase this value with the navigation button to 100 mbar, push to confirm, and select SAVE to save the setting.
6. The transmitter will return to the home screen. The measurement value at atmospheric pressure is now -100 mbar. At an applied pressure of 100 mbar the transmitter will display 0 mbar.

The menu zero adjustment also has the choice of **use process**. The transmitter can be adjusted to zero in a real process situation. When chosen, the transmitter will measure the pressure in an actual process. This measurement will be used as the zero value.

1. Navigate to program point **P101**, and push the button to enter the menu.
2. Choose **use process** , and push to confirm. The transmitter will display the actual measured value.
3. Push the navigation button to confirm, and select SAVE to save the setting.
4. The transmitter will return to the main menu.

6.2 SPAN ADJUSTMENT



This setting can be used to adjust the range (SPAN) according to an entered value or adjusted with or without an applied pressure. The maximum pressure which can be measured: The measurement at **ZERO (P101)** + the entered value **SPAN (P102)**. If the **ZERO (P101)** is increased then the maximum measured value will automatically be set higher at same rate as the zero.
This will be explained step by step by an example.

1. Example: Measurement range 100 – 2000 mbar.
2. The **span** must be set at 1900 mbar
3. The zero was set in the previous menu (**P101**) at 100 mbar.
4. Navigate to program point **P102 - SPAN Value**, and push the navigation button to enter the menu.
5. Two choices appear on the screen: **Set manual** and **Use process**.
6. Choose **Set manual**, a value will appear on the screen. (Depending on the transmitter range.)
7. Adjust the **SPAN** with the navigation button to 1900 mbar. and select SAVE to save the setting
8. The transmitter will return to the home screen.

The menu span adjustment also has the choice of "**use process**". The transmitter can be adjusted to the span in a real process situation. When chosen, the transmitter will measure the pressure in an actual process. This measurement will be used as the span value. (20 mA)

1. Navigate to program point **P102**, and push the button to enter the menu.
2. Choose "**use process**" , and push to confirm. The transmitter will display the actual measured value.
3. Push the navigation button to confirm, and select SAVE to save the setting.
4. The transmitter will return to the main menu.

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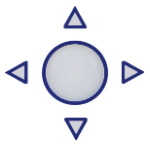
When a compound range must be adjusted (for example -1 till +3 bar), a span of 4 bar must be programmed.
The Zero (P101) must be set at -1 bar. The transmitter is adjusted at **- 1 bar = Zero** and **+3 bar = Span**.

If the process temperature at -1 bar is above 20 °C another filling oil must be applied inside the transmitter (Option G26).
If the process temperature at -0,5 bar is above 60 °C another filling oil must be applied inside the transmitter (Option G26).

6.3 CANCEL MOUNTING POSITION EFFECT



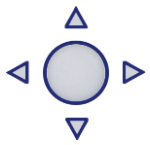
All transmitters are vertically calibrated. If the transmitter is installed horizontally, the transmitter has a small "mounting position" effect on the zero. The pressure value displayed, will be for example 0,002 mbar instead of 0,000 mbar. This effect can be neutralized within this menu.

1. Navigate to program point **P103 – MOUNT corr.**, and push the navigation button to enter the menu.
2. Two choices appear on the screen: **Set** and **Reset**
   Choosing **Set** will adjust the zero to 0,000 mbar in the mounting position when applicable.
   - Select **Set**, and push the button to confirm.
   - The Save icon will be displayed to indicate that the setting is saved.
   - The transmitter will return to the main menu.

   Choosing **Reset** will put the transmitter back to factory setting. (vertical adjustment)
   - Select **Reset**, and push the button to confirm, the setting will be put back to factory setting. The Save icon will be displayed to indicate that the setting is saved.
   - The transmitter will return to the main menu.

⚠ **CAUTION: Do not apply pressure while executing "Cancel mounting position effect"**

6.4 DISPLAY SETTING OF UNITS

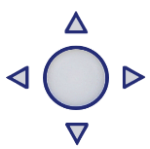


Various engineering units can be displayed on the display.
Factory setting = mbar

1. Navigate to program point **P104 – UNIT**, and push the navigation button to enter the menu.
2. Several engineering units can be selected. Each selected engineering unit is automatically converted to the correct value of the corresponding unit.
3. Navigate through this menu and choose the required unit, push to confirm.
4. The Save icon will be displayed to indicate that the setting is saved.
5. The transmitter will return to the main menu, the measured reading will be displayed in the chosen unit in the home screen.
6. The Analog Input Block parameters needs to adjusted accordingly.

⚠ **CAUTION: The selected pressure unit is only visible on the display when UNITS is chosen in program point P109 – Readout.**

6.5 OUTPUT SELECTION

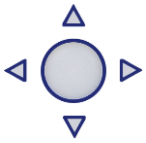


The scaling (only in percentage) can be set to 0 - 100 % and reversed 100 - 0 %. This will not affect the measuring value. The transmitter is standard set to 0%.

1. Navigate to program point **P105 – Reverse out**, and push the navigation button to enter the menu.
2. Two choices appear on the screen: **0 - 100 %** and **100 - 0 %.**
3. Make a choice and push to confirm.
4. The Save icon will be displayed to indicate that the setting is saved.
5. The transmitter will return to the main menu.

6. The Analog Input Block parameters needs to be adjusted accordingly.

6.6 DAMPING ADJUSTMENT

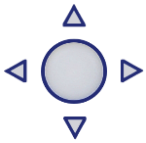


The transmitter has an adjustable damping between 0,00 to 25,00 seconds. Factory setting = 0,00 seconds

1. Navigate to program point **P106 – DAMPING**, and push the navigation button to enter the menu.
2. Two choices appear on the screen: **Set** and **Reset**
3. Make a choice and push to confirm.
   Choosing **Set** allows a value to be set between 0,00 and 25,00 seconds.
   - Select Set, and push the button to confirm.
   - Adjust the damping with the navigation button, push to confirm.
   - The Save icon will be displayed to indicate that the setting is saved.
   - The transmitter will return to the main menu.

   Choosing **Reset** will put the setting back to factory setting (0,0 seconds)
   - Select Reset, and push the button to confirm.
   - The Save icon will be displayed to indicate that the setting is saved, the setting will be put back to factory setting 0,00 s.
   - The transmitter will return to the main menu.

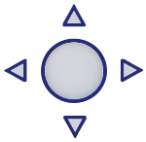
6.7 LANGUAGE



In this menu the preferred menu language can be selected.

1. Navigate to program point **P107 - LANGUAGE**, and push the navigation button to enter the menu.
2. Seven choices appear on the screen: **English**, **Dutch**, **Spanish**, **German**, **Russian, Polish** and **French**.
3. Make a choice and push to confirm.
4. The Save icon will be displayed to indicate that the setting is saved.
5. The transmitter will return to the main menu.

6.8 DEVICE SETUP



In this menu, several operational settings can be made for the transmitter and the display.

1. Navigate to program point **P108 – Device Setup**, and push the navigation button to enter the menu.
2. Six choices appear on the screen: **Protection** - **Backlight** - **Temp units** – **Temp min/max** – **Sec. Value** and **PA OUT_SCALE**.
   Choose the desired option and push to confirm.
3. Below are the choices displayed. They can be selected and configured using the navigation button.
   - **Protection**: Open and Protected: Local protection for adjusting settings locally on the transmitter. When exceeding limits, a warning symbol will display on the screen.
   - **Backlight**: Choice between: **On**, **Sleep mode** (Turn off backlight after 5 minutes) and **Off**.
   - **Temp units:** Choice between: **Celsius** and **Fahrenheit**.
   - **Temp min/max:** Two choices appear on the screen: **Readout** and **Reset**
     By choosing **Readout** the last measured minimum and maximum temperature values of process and ambient appear. For the process temperature, a new value is

stored in a change of temperature more than 2 °C. For the ambient temperature this is 5˚ C. By choosing **Reset** the previous stored values will be deleted.

- **Sec. Value:** Three choices appear on the screen for the secondary readout on the main screen: **Unit**, **Rate** and **Temperature**.
- **PA OUT_SCALE:** In this menu scaling options for the Analog Input block (Profibus Output) can be configured locally on the transmitter. Two choices appear on the screen: **Set 1:1** and **Set manual**.
    - With option **Set 1:1** a scaling can be set with the following menu choices: **EU100**, **EU0** and **Unit**. As standard the values are the same as the last saved Zero, Span and engineering unit (P109 must be set to **unit** or **percentage**).
      Select **EU100** to enter a value for the 100% scaling point.
      Select **EU0** to enter a value for the 0% scaling point.
      Select **Unit** to enter the engineering unit code.

    - With option **Set manual** the current scaling configuration (Profibus output) is shown. Set manual should only be used for units not supported by the Series 4000, or when a different scaling then the local readout is needed on the Profibus output. **The engineering units can be found in the attachment of this manual or on www.klay.nl under section downloads.**

      The engineering units can be found in the attachment of this manual or in the digital version on www.klay.nl under section downloads.

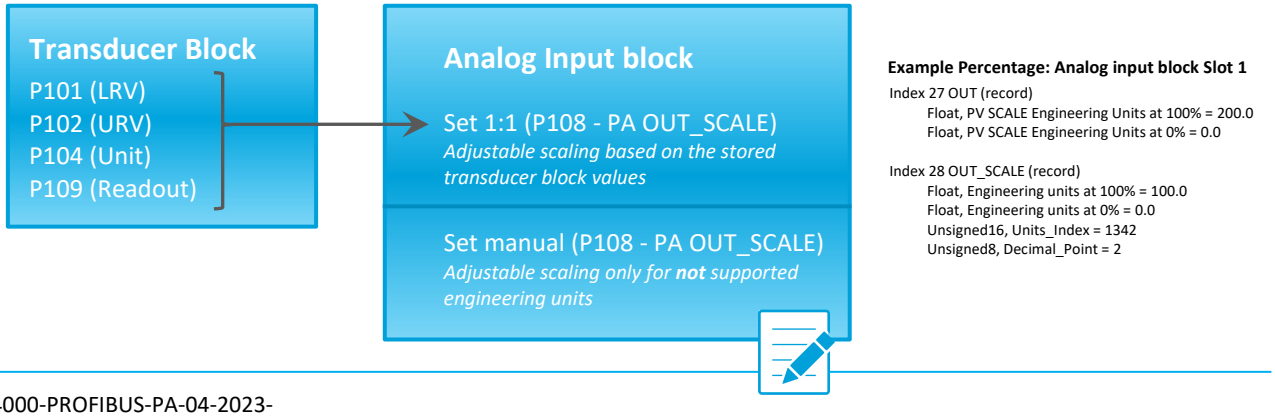
Profibus scaling will be explained step by step by the following examples:

Scaling Example - Pressure:

- Configure the Zero - P101 (If necessary)
- Configure the Span - P102 (If necessary)
- Select *mbar* in program point P104 (or any other pressure unit)
- Select *Unit* in program point P109
- Navigate to program point P108 and select **PA OUT_SCALE**
- Configure the scale with **Set 1:1**, navigate to save, to save the setting.
- The transmitter will restart to load the new scale.

Scaling Example - Percentage:

- Configure the Zero - P101 (If necessary)
- Configure the Span - P102 (If necessary)
- Select *Percentage* in program point P109
- Navigate to program point P108 and select **PA OUT_SCALE**
- Configure the scale with **Set 1:1**, navigate to save, to save the setting.
- The transmitter will restart to load the new scale.

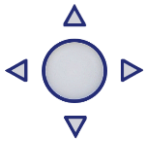


⚠ **CAUTION: Do not change the Zero, Span, Unit or Readout (P109) after configuring the Profibus Out scaling, as described above. Changing will result in invalid Profibus communication.**

P109 Readout

6.9 READOUT

In this menu, the readout on the display is determined. This is the type of measurement appearing on the home screen. Factory Setting = Unit



1. Navigate **P109 – READOUT**, and push the navigation button to enter the menu.
2. Eight choices appear on the screen:
   Unit = Pressure unit as chosen in **P104**
   Percentage = 0 - 100%
   Temperature = Actual sensor temperature (°C or F) *
   Hectoliter = Number of hectoliters (only possible in combination with linearization P110)
   Cubic meter = Number of cubic meters (in combination with linearization P110)
   Liter = Number of liters (only possible in combination with linearization P110)
   Kilogram = Number of kilograms (only possible in combination with linearization P110)
   After selecting this readout the **S**pecific **G**ravity of the medium (**SG** = g/cm^3) must be entered with a value between 0.2 and 4.0 g/cm^3. The specific gravity will appear on the home screen (g/cm^3) under the primary selected readout. This readout will be indicated as a linear measurement, and displayed by the symbol on the home screen.
   Tons = Number of tons (only possible in combination with linearization P110)
   After selecting this readout the **S**pecific **G**ravity of the medium (**SG** = g/cm^3) must be entered with a value between 0.2 and 4.0 g/cm^3. This readout will be indicated as a linear measurement, and displayed by the symbol on the home screen. The specific gravity will appear on the home screen (g/cm^3) under the primary selected readout.
3. Navigate to the desired choice, confirm the selection by pushing the navigation button. The Save icon will be displayed to indicate that the setting is saved.
4. The transmitter will return to the main menu.
5. The Analog Input Block parameters needs to adjusted accordingly.

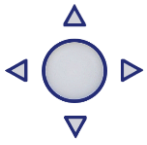
*(Indication of process temperature, accuracy depending on sensor position)

⚠ ***For measuring weight (Kg and Tons), a reliable accuracy cannot be guaranteed, the Series 4000 pressure transmitter cannot compensate for Specific Gravity changes or any thermal increase or decrease.***

P110 Tank lin.

6.10 TANK LINEARIZATION

In this menu, various tank linearization's can be selected.
Factory setting = No linearization The volume as a measured value will be displayed on the home screen. (set in **P104)** The values (configured in the following settings) must be in meters. Only for local use, not compatible with Profibus.



1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu. Six choices appear on the screen:
   No Lin = No linearization
   Hor. Tank = Linearization setting for a horizontal tank: cylindrical and elliptic
   Vert. Cone = Linearization setting for a vertical tank with a conical bottom.
   Vert. Sphere = Linearization setting for a vertical tank with a spherical bottom.
   Vert. Trunc = Linearization setting for a vertical tank with a truncated bottom**.**
   Free lin = Free linearization setting, adjustable in 100 free programmable points.

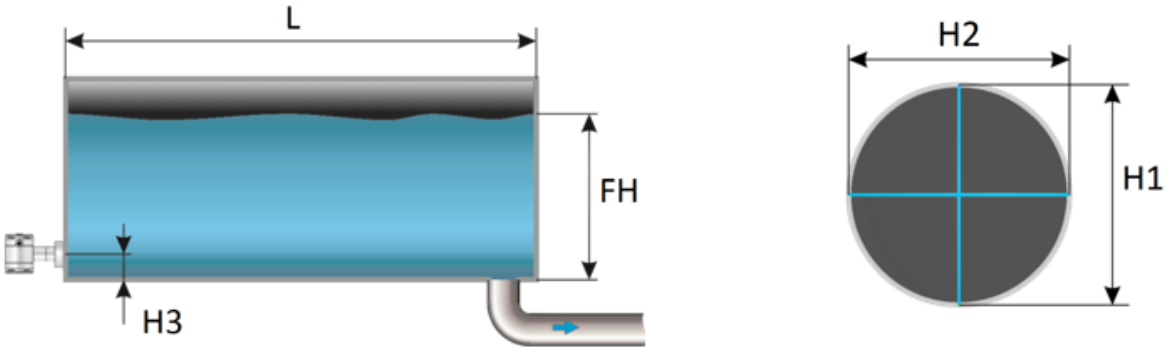
LINEARIZATION DISABLE

With the choice **No. Lin**. an existing linearization can be turned off and can be identified by the symbol on the home screen:
Linearization can be recognized by the following symbol on the home screen:

1. Select **No Lin.** and confirm this with the button.
2. The Save icon will be displayed to indicate that the setting is saved.

The following pages describe the setting for each type of linearization.

LINEARIZATION HORIZONTAL TANK (WITH FLAT END)



1. Navigate to **Hor. Tank**. with the navigation button, and push to confirm.
2. Two choices appear on the screen: **Input** and **Simulate**
3. Select **Input**, and push to confirm.
4. Six choices appear on the screen:

Display	Drawing	Explanation
Length	**L**	The length of the tank
Height 1	**H1**	The height of the tank
Height 2	**H2**	The diameter of the tank (with a cylindrical tank, this is equal to the height of the tank)
Height 3	**H3**	The height till the topside of the diaphragm (or weld-on nipple)
Height 4	**H4**	Value must be 0
Fill Height	**FH**	The maximum percentage of filling of the tank

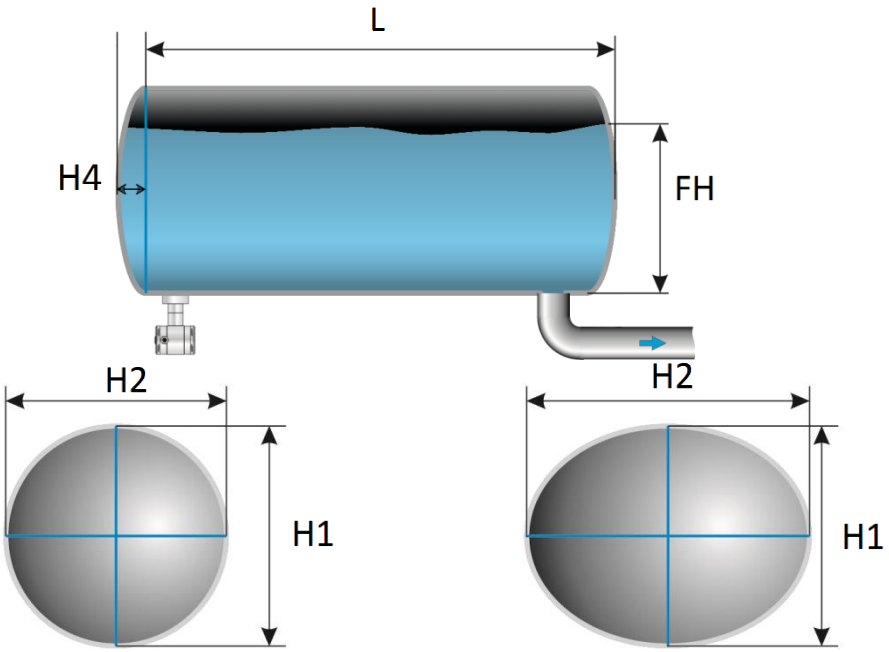
5. Fill in each value except Height 4, and confirm each selection with the control button. The values must be entered in meters.
6. Select SAVE to save the setting.
7. The transmitter will return to the main menu.

SIMULATION

After linearization is entered and stored, it is possible to perform a simulation based on the entered value's. Based on the value entered in mWc, the transmitter will display the number of hectoliters (on the basis of the specified linearization values).

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Hor. Tank**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Input** and **Simulate**
4. Select **Simulate**, and push to confirm.
5. Fill in the desired value based on mWc, the number of hectoliters change directly with a change in the value mWc.

LINEARIZATION HORIZONTAL TANK WITH A PARABOLIC END (CYLINDRICAL OR ELLIPTIC)



1. Navigate to **Hor. Tank**. with the navigation button, and push to confirm.
2. Two choices appear on the screen: **Input** and **Simulate**
3. Select **Input**, and push to confirm.
4. Six choices appear on the screen:

	Display	Drawing	Explanation
	Length	**L**	The length of the tank
	Height 1	**H1**	The height of the tank
	Height 2	**H2**	The diameter of the tank (with a cylindrical tank, this is equal to the height of the tank)
	Height 3	**H3**	The height till the topside of the diaphragm (or weld-on nipple)
	Height 4	**H4**	The length of **1** parabolic end of the cylinder
	Fill Height	**FH**	The maximum percentage of filling of the tank

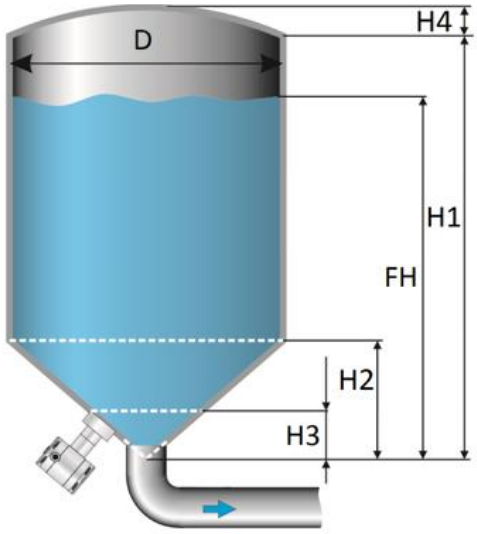
5. Fill in each value, and confirm with the navigation button. **The entered value's must be in meters.**
6. Select SAVE to save the setting.
7. The transmitter will return to the main menu.

SIMULATION

After linearization is entered and stored, it is possible to perform a simulation based on the entered value's. Based on the value entered in mWc, the transmitter will display the number of hectoliters (on the basis of the specified linearization values).

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Hor. Tank**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Input** and **Simulate**
4. Select **Simulate**, and push to confirm.
5. Fill in the desired value based on mWc, the number of hectoliters change directly with a change in the value mWc.

LINEARIZATION VERTICAL TANK WITH A CONICAL BOTTOM



1. Navigate to **Vert. Sphere**. with the navigation button, and push to confirm.
2. Two choices appear on the screen: **Input** and **Simulate**
3. Select **Input**, and push to confirm.
4. Six choices appear on the screen:

Display	Drawing	Explanation
Height1	**H1**	The height of the tank
Diameter	**D**	The diameter of the tank
Height 2	**H2**	the height of the cone
Height 3	**H3**	The height till the topside of the diaphragm
Height 4	**H4**	The height of the parabolic tank roof
Fill Height	**FH**	The maximum percentage of filling of the tank

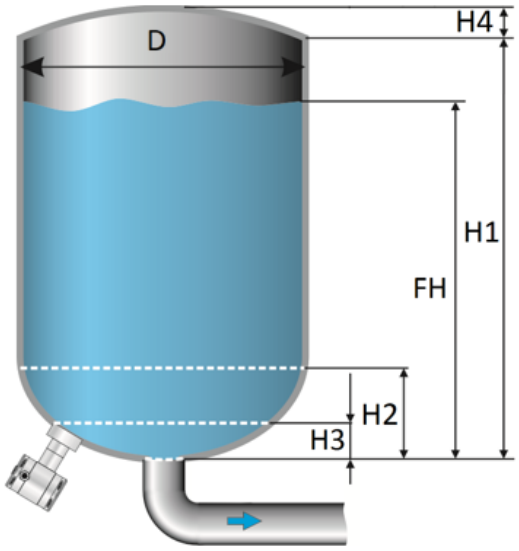
5. Fill in each value, and confirm with the navigation button. **The entered value's must be in meters.**
6. Select SAVE to save the setting.
7. The transmitter will return to the main menu.

SIMULATION

After linearization is entered and stored, it is possible to perform a simulation based on the entered value's. Based on the value entered in mWc, the transmitter will display the number of hectoliters (on the basis of the specified linearization values).

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Vert. Sphere**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Input** and **Simulate**
4. Select **Simulate**, and push to confirm.
5. Fill in the desired value based on mWc, the number of hectoliters change directly with a change in the value mWc.

LINEARIZATION VERTICAL TANK WITH A SPHERICAL BOTTOM



1. Navigate to **Vert. Cone**. with the navigation button, and push to confirm.
2. Two choices appear on the screen: **Input** and **Simulate**
3. Select **Input**, and push to confirm.
4. Six choices appear on the screen:

Display	Drawing	Explanation
Height1	**H1**	The height of the tank
Diameter	**D**	The diameter of the tank
Height 2	**H2**	the height of the spherical bottom
Height 3	**H3**	The height till the topside of the diaphragm
Height 4	**H4**	The height of the parabolic tank roof
Fill Height	**FH**	The maximum percentage of filling of the tank

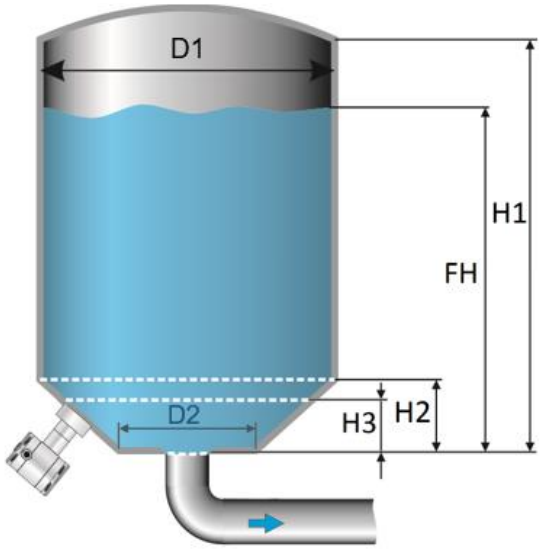
5. Fill in each value, and confirm with the navigation button. **The entered value's must be in meters.**
6. Select SAVE to save the setting.
7. The transmitter will return to the main menu.

SIMULATION

After linearization is entered and stored, it is possible to perform a simulation based on the entered value's. Based on the value entered in mWc, the transmitter will display the number of hectoliters (on the basis of the specified linearization values).

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Vert. Cone**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Input** and **Simulate**
4. Select **Simulate**, and push to confirm.
5. Fill in the desired value based on mWc, the number of hectoliters change directly with a change in the value mWc.

LINEARIZATION VERTICAL TANK WITH A TRUNCATED BOTTOM



1. Navigate to **Vert. Trunc**. with the navigation button, and push to confirm.
2. Two choices appear on the screen: **Input** and **Simulate**
3. Select **Input**, and push to confirm.
4. Six choices appear on the screen:

Display	Drawing	Explanation
Height1	**H1**	The height of the tank
Diameter 1	**D1**	The diameter of the tank
Height 2	**H2**	the height of the cone
Height 3	**H3**	The height till the topside of the diaphragm
*Diameter 2	**D2**	The diameter of the truncated bottom
Fill Height	**FH**	The maximum percentage of filling of the tank

5. Fill in each value, and confirm with the navigation button. **The entered value's must be in meters.**
6. Select SAVE to save the setting.
7. The transmitter will return to the main menu

***It's also possible that Height 4 (H4) is visible on the screen. There is nothing wrong. Diameter D2 is the same value as Height H4. You can fill in the same value.**

SIMULATION

After linearization is entered and stored, it is possible to perform a simulation based on the entered value's. Based on the value entered in mWc, the transmitter will display the number of hectoliters (on the basis of the specified linearization values).

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Vert. Trunc**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Input** and **Simulate**
4. Select **Simulate**, and push to confirm.
5. Fill in the desired value based on mWc, the number of hectoliters change directly with a change in the value mWc.

FREE LINEARIZATION

FREE LINEARIZATION IN PROCESS

1. Navigate to program point **P110 – TANK LIN,** and push to confirm.
2. Navigate to **Free lin**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Measured** and **Manual**
4. Select **Measured** to configure a free linearization in a process situation.
5. Two choices appear on the screen**: Input** and **Simulate**
6. Select **Input**, and push to confirm
7. Five choices appear on the screen:

Clear table: The previous entered values for linearization will be deleted. It is advisable to use this feature for each time a new linearization is configured.

⚠ **All entered values and dimensions of an existing / previous linearization will be erased.**

Volume units: Select the preferred unit**:** Liters, Hectoliters, Kg and Tons (after linearization the unit can be changed and selected in **P109**)
Height: The height of the tank can be filled in (highly recommended for an accurate linearization). The transmitter will determine with this height the span. A linearization will be made with the smallest possible deviation. *Factory setting = Saved span in P102.*
Start Point: The filling of a tank can be measured up to 70 points. The transmitter must be installed in an actual process to accomplish these measurements. The measuring must take place from low to high. (Filling an empty tank). The actual measuring will be displayed on the screen in percentage (%) for **Xn** (filling) and for **Yn** the measured volume. To enter the next measured point move the navigation button up and enter the values.
Save: When all desired measurements are completed and all parameters have been set, the linearization must be saved. Push the navigate button to the left and select SAVE to save the linearization. The transmitter will return to the main menu.

⚠ WARNING AND PRECAUTIONS

- When a tank filling (**Xn**) does not reach 100 % of the height of the tank, the transmitter will calculate the remaining part. This calculating method is linear and will only be used for the remaining part up to 100 %.

- It is not advisable to manually adjust the SPAN in program point P102 after a linearization has been configured. If the SPAN is adjusted after a linearization configuration, a warning will appear on the screen when entering P102.

- When the a free linearization is used for measuring weight (Kg and Tons), a reliable accuracy cannot be guaranteed due to external influences such as heat and tank wall expansion. **The change of Specific Gravity due to different temperatures cannot be compensated by the Series 4000 pressure transmitter.**

SIMULATION

After linearization is entered and saved, it is possible to perform a simulation. (Based on the saved linearization) The transmitter will convert the entered mWc to hectoliters.

FREE LINEARIZATION MANUALLY

When it's not possible to enter and measure for a linearization in an actual process condition, a free linearization can be configured manually. Known measurements values and volumes must be entered manually in the transmitter.

1. Navigate to program point **P110 – TANK LIN,** and push the navigation button to enter the menu.
2. Navigate to **Free lin**. with the navigation button, and push to confirm.
3. Two choices appear on the screen: **Measured** and **Manual**
4. Select **Manual** to configure a free linearization manually.
5. Two choices appear on the screen: **Input** and **Simulate**
6. Select **Input**, and push to confirm.
7. Five choices appear on the screen:

Clear table: The previous entered values for linearization will be deleted. It is advisable to use this feature for each time a new linearization is configured.

⚠ **All entered values and dimensions of an existing / previous linearization will be erased.**

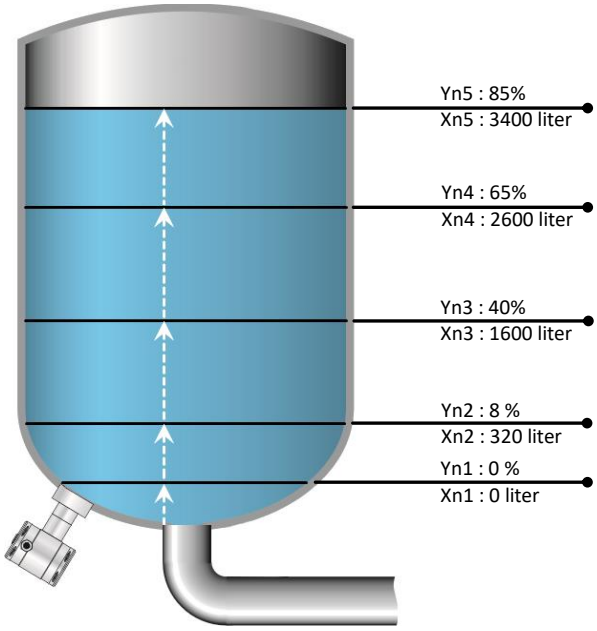
Volume units: Select the preferred unit**:** Liters, Hectoliters, Kg and Tons (after linearization the unit can be changed and selected in **P109**)

Height: The height of the tank can be filled in (highly recommended for an accurate linearization). The transmitter will determine with this height the span. A linearization will be made with the smallest possible deviation. *Factory setting = Saved span in P102.*

Start Point: The contents of a tank can be configured up to 70 points. The entered value's must be from low to high (Filling an empty tank). The manually entered values will be displayed on the screen in percentage (%) for **Xn** and for **Yn** in Hectoliters. To enter the next measured point move the navigation button up and enter the values.

Example: *A tank filling must programmed in the transmitter.*

- *Choose **Clear Table** to remove all possible previous settings.*
- *Choose the preferred **Volume units.***
- *Fill in the **Height** of the tank (highly recommended for an accurate linearization).*
- *In menu **Start Point** the linearization points can be filled in. In **Xn1** the percentage of the filling must be filled in. In **Yn1** the corresponding volume. After this, there are 69 more linearization points available.*
- *When all (needed) points are filled in, the linearization must be saved. Push the navigation button to the left and select SAVE to save this linearization.*



The figure above shows a tank with standard dimensions. Free linearization can applied on a wide variety of tanks with non-standard dimensions.

Save: When all desired measurements are completed and all parameters have been set, the linearization must be saved. Push the navigation button to the left to Exit and select SAVE to save the linearization. The transmitter will return to the main menu.

⚠ WARNING AND PRECAUTIONS

- When a tank filling (**Xn**) is not configured till 100 %, the transmitter will calculate the remaining part. This calculating method is linear and will only be used for the remaining part up to 100 %.

- It is not advisable to manually adjust the SPAN in program point P102 after a linearization has been configured. If the SPAN is adjusted after a linearization configuration, a warning will appear on the screen when entering P102.

- When the a free linearization is used for measuring weight (Kg and Tons), a reliable accuracy cannot be guaranteed due to external influences such as heat and tank wall expansion. **The change of Specific Gravity due to different temperatures cannot be compensated by the Series 4000 pressure transmitter.**

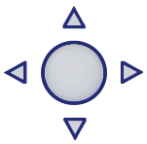
SIMULATION
After linearization is entered and stored, it is possible to perform a simulation. (Based on the stored linearization) The transmitter will convert the entered mWc to hectoliters.

⚠ **As an option the Series 4000 and 4000-SAN can be delivered with option G171. This is a special setting of the software, enabling the display to show a reading in weight units.**

P111 Information

6.11 INFORMATION

This menu shows a collection of information from the transmitter and contact information from the manufacturer.



1. Navigate to program point **P111 - Information** and push the navigation button to enter the menu.
2. Push the navigation button up and down to see all of the information
3. Push the button to leave this menu. Below is a representation of this information screen:

```
Klay Instruments
www.klay.nl
+31521591550
Version              -      Software revision
Pa Version           -      3.02
No:                  -      Serial number transmitter
Zero                 -      Zero (bar)
Span                 -      Span (bar)
Damping              -      Damping (in seconds)
Local Prot           -      Protection On or Off
Sec. Value           -      Selected secondary configuration
Backlight            -      Backlight On, Sleep mode or Off
Temp                 -      Temperature unit Celsius or Fahrenheit
Print                -      Production code
Supply               -      Production code
Display              -      Production code
```

P112 Calibrate

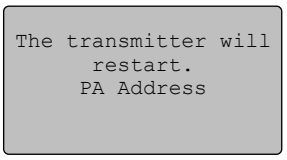
6.12 CALIBRATE

Only available for the manufacturer.

6.13 PA ADDRESS

In this menu a PA Address from 2 till 126 can be selected.

1. Navigate to program point **P113 - PA Address** and push the navigation button to enter the menu.
2. Select the address with the navigation button and push to confirm. Select SAVE to save the setting.
3. The following message appear on the display:
4. The transmitter will automatically restart
5. The changed address is displayed in the startup screen.



6.14 FACTORY

Only available for the manufacturer.

7. PROFIBUS® PA

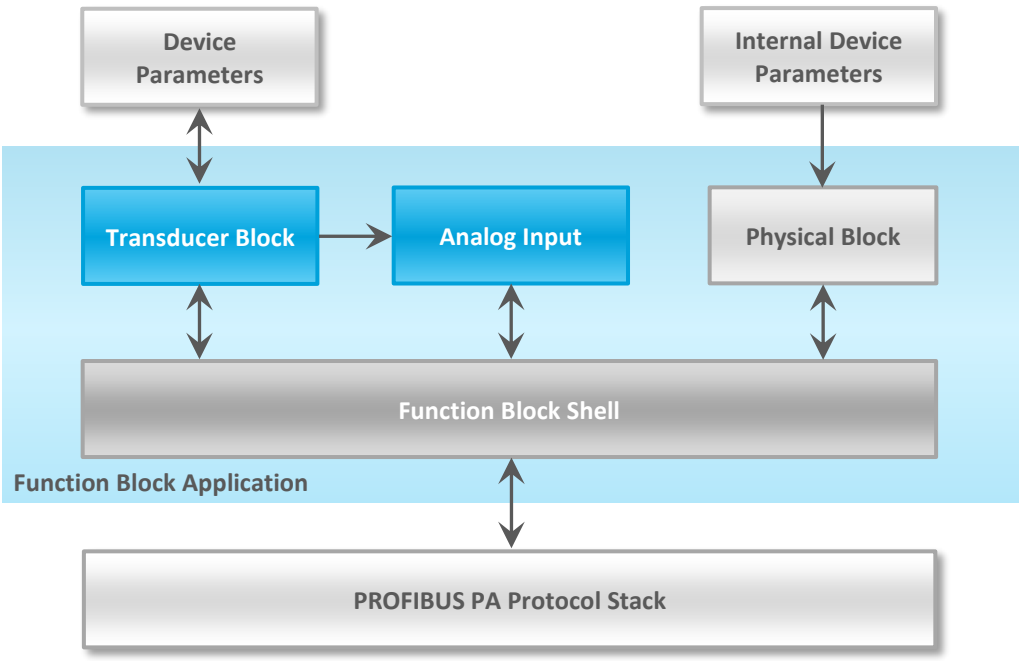
7.1 PA INTERFACE

The Series 4000-PROFIBUS PA is developed as a PROFIBUS® Slave device. A slave device is a addressable peripheral device which reads process information and delivers output information to the Master device in the PROFIBUS® system. The Series 4000 is developed for Profibus PA Profile V3.02 and is backwards compatible with Profile version V3.01.

The Series 4000 supports 2 communication layers:

- **DP-V0**: **Cyclic exchange** of process data and exchanging diagnosis functions between master and slaves.
- **DP-V1**: **Acyclic data exchange** and alarm handling between master and slaves for diagnosis, control, monitoring and alarm handling of the slaves in parallel with cyclic data traffic.

The PROFIBUS® PA network is standardized using a block models. The different block types are explained below.



Block Type	Description
Function Block	Control system behavior like for example: Analog Input, Analog Output, Discrete Input, Discrete Output and Totalizer.
Transducer Block	Converting mapping between process data and Function Blocks. The Transducer Block is used to perform preprocessing and calibration parameters of device data according to specific device settings. At least one Transducer Block has to be available for a PROFIBUS® PA field device.
Physical Block	Describes the specific data identifying the individual physical device properties such as the device name, manufacturer, and serial number.

Physical Block Parameters (Slot 0)

In the table below the Physical Block parameters.

Index	Name	Type	Description
16	BLOCK_OBJECT	Record	Block object
	Reserved	Unsigned8	0
	Block_Object	Unsigned8	0x01, physical block
	Parent_Class	Unsigned8	0x01, Transmitter
	Class	Unsigned8	250, not used
	Dev_Rev	Unsigned16	1
	Dev_Rev_Comp	Unsigned16	1
	DD_Revision	Unsigned16	0
	Profile	OctetString(2)	MSB: 0x40 -> Number of the PROFIBUS PA profiles within PI Profile Class 64 LSB: 0x02 -> Class B
	Profile_Revision	Unsigned16	0x302: PA Prfile Revision 3.02
	Execution_Time	Unsigned8	0
	Number_of_Parameters	Unsigned16	29, number of parameters
	Address_of_View_1	Unsigned16	0x00F8, View_1 has an index 248
	Number_of_Views	Unsigned8	1, only one View_1 in Device
17	ST_REV	Unsigned16	ST_REV shall be incremented at least by one if at least one static parameter in the corresponding block has been modified
18	TAG_DESC	OctetString(32)	
19	STRATEGY	Unsigned16	
20	ALERT_KEY	Unsigned8	
21	TARGET_MODE	Unsigned8	Target mode
22	MODE_BLK	Record	
	Actual_mode	Unsigned8	Actual mode
	Permitted_mode	Unsigned8	Permitted mode
	Normal_mode	Unsigned8	Normal mode
23	ALARM_SUM	Record	
	Current	OctetString(2)	Current alarm
	Unacknowledged	OctetString(2)	Unacknowledged alarm
	Unreported	OctetString(2)	Unreported alarm
	Disabled	OctetString(2)	Disabled alarm
24	SOFTWARE_REVISION	VisibleString(16)	Revision-number of the software of the field device
25	HARDWARE_REVISION	VisibleString(16)	Revision-number of the hardware of the field device
26	DEVICE_MAN_ID	Unsigned16	Identification code of the manufacturer of the field device

27	DEVICE_ID	VisibleString(16)	Manufacturer specific identification of the device
28	DEVICE_SER_NUM	VisibleString(16)	Serial number of the field device
29	DIAGNOSIS	OctetString(4)	Detailed information of the device, bitwize coded. More than one message possible at once.
30	DIAGNOSIS_EXT	OctetString(6)	Additional manufacturer-specific information of the device, bitwize coded. More than one message possible at once.
31	DIAGNOSIS_MASK	OctetString(4)	Definition of supported DIAGNOSIS information-bits (0: not supported, 1: supported)
32	DIAGNOSIS_MASK_EXT	OctetString(6)	Definition of supported DIAGNOSIS_EXTENSION information-bits (0: not supported, 1: supported)
33	DEVICE_CERTIFICATION	VisibleString(32)	Certifications of the field device, e.g. EX certification
34	WRITE_LOCKING	Unsigned16	Software write protection
35	FACTORY_RESET	Unsigned16	Parameter for the device resetting
36	DESCRIPTOR	OctetString(32)	
37	DEVICE_MESSAGE	OctetString(32)	
38	DEVICE_INSTAL_DATE	OctetString(16)	
39	NULL_PARAM		Optional parameter LOCAL_OP_ENA isn't implemented
40	IDENT_NUMBER_SELECT		
41	NULL_PARAM		Optional parameter HW_WRITE_PROTECTION isn't implemented
42	FEATURE	Record	Indicates optional features implemented in the device and the status of these features which indicates if the feature is supported or not supported.
	Supported	OctetString(4)	Supported features
	Enabled	OctetString(4)	Enabled features
43	COND_STATUS_DIAG	Unsigned8	Indicates the mode of a device that can be configuredfor status and diagnostic behavior
44	DIAG_EVENT_SWITCH	Record	Indicates / controls the reaction of the device on device specific diagnostic events if FEATURE.Enabled.Condensed_Status = 1
	Diag_Status_Link	Unsigned8-Array(48)	Array of switches for device specific diagnostic events. Mapping to diagnosis bit and status code
	Slot	Unsigned8	Slot of the continuation of Diag_Event_Switches. Points to the next Diag_Event_Switch structure
	Index	Unsigned8	Index (absolute) of the continuation of Diag_Event_Switches. Points to the next Diag_Event_Switch structure.

Transducer Block Parameters (Slot 5)

In the table below the Transducer Block is shown with the specific Device Configuration parameters. Index parameters 25, 27, 43, 44, 45, 53 and 54 can only be configured when transmitter is set to **Out of Service** (OOS). The transducer block can be set to Out of Service in index number 21. After configuring the transducer block, index number 21 must be set to **AUTO**.

Index	Name	Type	Description
16	BLOCK_OBJECT	Record	Block object
	Reserved	Unsigned8	0
	Block_Object	Unsigned8	0x03, transducer block
	Parent_Class	Unsigned8	244, manufacture specific
	Class	Unsigned8	250, not used
	Dev_Rev	Unsigned16	1
	Dev_Rev_Comp	Unsigned16	1
	DD_Revision	Unsigned16	0

	Profile	OctetString(2)	MSB: 0x40 -> Number of the PROFIBUS PA profiles within PI Profile Class 64 LSB: 0x02 -> Class B
	Profile_Revision	Unsigned16	0x302: PA Profile Revision 3.02
	Execution_Time	Unsigned8	0
	Number_of_Parameters	Unsigned16	52, number of parameters
	Address_of_View_1	Unsigned16	0x05F8, View_1 has an index 248
	Number_of_Views	Unsigned8	1, one View_1
17	ST_REV	Unsigned16	ST_REV shall be incremented at least by one if at least one static parameter in the corresponding block has been modified
18	TAG_DESC	OctetString(32)	
19	STRATEGY	Unsigned16	
20	ALERT_KEY	Unsigned8	
21	TARGET_MODE	Unsigned8	Target mode
22	MODE_BLK	Record	
	Actual_mode	Unsigned8	Actual mode
	Permitted_mode	Unsigned8	Permitted mode
	Normal_mode	Unsigned8	Normal mode
23	ALARM_SUM	Record	
	Current	OctetString(2)	Current alarm
	Unacknowledged	OctetString(2)	Unacknowledged alarm
	Unreported	OctetString(2)	Unreported alarm
	Disabled	OctetString(2)	Disabled alarm
24	PRIMARY_VALUE	Record	Primary value and status (Pressure)
	Value	Float	Primary value
	Status	Unsigned8	Primary status
25	PV_UNIT	Unsigned16	Primary value unit (Pressure engineering units)
26	SECONDARY_VALUE	Record	Secondary value and status (Process Temperature)
	Value	Float	Secondary value
	Status	Unsigned8	Secondary status
27	SV_UNIT	Unsigned16	Secondary value unit (Temperature units)
28	TERTIARY_VALUE	Record	Tertiary value and status (Ambient Temperature)
	Value	Float	Tertiary value
	Status	Unsigned8	Tertiary status
29	TV_UNIT	Unsigned16	Tertiary value init (Temperature units)
30	QUATERNARY_VALUE	Record	Quaternary value and status (Pressure)
	Value	Float	Quaternary value
	Status	Unsigned8	Quaternary status
31	QV_UNIT	Unsigned16	Quaternary value unit (Pressure engineering units)
32	INTERNAL_MAN_ID	Unsigned16	INTERNAL device manufacture ID
33	INTERNAL_DEV_TYPE	Unsigned16	INTERNAL device type
34	INTERNAL_DEV_ID	Unsigned32	INTERNAL device ID
35	INTERNAL_DEV_REV	Unsigned8	INTERNAL device revision
36	INTERNAL_SW_REV	Unsigned8	INTERNAL device software revision
37	INTERNAL_HW_REV	Unsigned8	INTERNAL device hardware revision
38	INTERNAL_TAG_DESC_DATE	Record	INTERNAL TAG, Descriptor and Date record
	Tag	VisibleString(8)	INTERNAL tag
	Descriptor	VisibleString(16)	INTERNAL descriptor
	Day	Unsigned8	Day
	Month	Unsigned8	Month
	Year	Unsigned8	Year
39	INTERNAL_CMD_MAJOR_REV	Unsigned8	INTERNAL command major revision
40	INTERNAL_MESSAGE	VisibleString(32)	INTERNAL message
41	SIMULATION_VALUE	Record	Simulation value and status
	Value	Float	Simulation value

	Status	Unsigned8	Simulation status
42	COMM_STATE	Unsigned8	INTERNAL communication status
43	PV LRV	Float	Transducer Lower Range Value (Zero)
44	PV URV	Float	Transducer Upper Range Value (Span)
45	PV DAMPING VALUE	Float	PV damping value in seconds
46	RESERVED	Float	
47	RESERVED	Float	
48	RESERVED	Float	
49	RESERVED	Float	
50	RESERVED	Float	
51	RESERVED	Float	
52	RESERVED	Float	
53	PV MOUNT CORRECTION	Unsigned16	(0: reset, 1: correct mounting effect with measured pressure)
54	DEVICE SETTINGS	Unsigned16	Bitmapped structure Bit 0 = Reverse Output Bit 1 = Secondary display reading Bit 2-3 = Backlight Bit 4-6 = Language Bit 7-10 = Primary display reading Bit 11-15 = Reserved
55	RESERVED	Unsigned16	
56	RESERVED	Unsigned16	
57	RESERVED	Unsigned16	
58	RESERVED	Unsigned16	
59	RESERVED	Unsigned16	
60	RESERVED	Unsigned16	
61	RESERVED	Unsigned32	
62	RESERVED	Unsigned32	
63	RESERVED	Unsigned32	
64	RESERVED	Unsigned32	
65	RESERVED	Unsigned32	
66	RESERVED	OctetString(32)	
67	RESERVED	OctetString(32)	

Analog Input Block Parameters (Slot 1 - 4)

In the table below the Analog Input Block parameters.

Index	Name	Type	Description
16	BLOCK_OBJECT	Record	Block object
	Reserved	Unsigned8	0
	Block_Object	Unsigned8	0x02, function block
	Parent_Class	Unsigned8	0x01, input
	Class	Unsigned8	0x01, analog input
	Dev_Rev	Unsigned16	1
	Dev_Rev_Comp	Unsigned16	1
	DD_Revision	Unsigned16	0
	Profile	OctetString(2)	MSB: 0x40 -> Number of the PROFIBUS PA profiles within PI Profile Class 64 LSB: 0x02 -> Class B
	Profile_Revision	Unsigned16	0x302: PA Prfile Revision 3.02
	Execution_Time	Unsigned8	0
	Number of Parameters	Unsigned16	45, number of parameters
	Address_of_View_1	Unsigned16	(0x01F8,0x02F8, 0x03F8, 0x04F8 for different AI blocks) View_1 has an index 248
	Number_of_Views	Unsigned8	1, only one View_1 in Device

17	ST_REV	Unsigned16	ST_REV shall be incremented at least by one if at least one static parameter in the corresponding block has been modified
18	TAG_DESC	OctetString(32)	
19	STRATEGY	Unsigned16	
20	ALERT_KEY	Unsigned8	
21	TARGET_MODE	Unsigned8	Target mode
22	MODE_BLK	Record	
	Actual_mode	Unsigned8	Actual mode
	Permitted_mode	Unsigned8	Permitted mode
	Normal_mode	Unsigned8	Normal mode
23	ALARM_SUM	Record	
	Current	OctetString(2)	Current alarm
	Unacknowledged	OctetString(2)	Unacknowledged alarm
	Unreported	OctetString(2)	Unreported alarm
	Disabled	OctetString(2)	Disabled alarm
24	BATCH	Record	Batch structure
	Batch_ID	Unsigned32	Identifies a certain batch to allow assignment of equipment-related information (e.g. faults, alarms ...) to the batch
	Rup	Unsigned16	No. of Recipe Unit Procedure or of Unit
	Operation	Unsigned16	No. of Recipe Operation
	Phase	Unsigned16	No. of Recipe Phase
25	NULL_PARAM	--	
26	OUT	Record	Output of the AI block
	Value	Float	Output value
	Status	Unsigned8	Output status
27	PV_SCALE	Array	Conversion of the Process Variable into percent using the high and low scale values
	PV_SCALE.EU_at_100%	Float	Element 0 of the array: value at EU of 100%
	PV_SCALE.EU_at_0%	Float	Element 1 of the array: value at EU of 0%
28	OUT_SCALE	Record	Scale of the Process Variable
	EU_at_100%	Float	
	EU_at_0%	Float	
	Units_Index	Unsigned16	
	Decimal_Point	Unsigned8	
29	LIN_TYPE	Unsigned8	Type of linearization
30	CHANNEL	Unsigned16	Reference to the active Transducer Block which provides the measurement value to the Function Block
31	NULL_PARAM	--	
32	PV_FTIME	Float	Filter time of the Process Variable
33	FSAFE_TYPE	Unsigned8	Defines the reaction of the device, if a fault is detected
34	FSAFE_VALUE	Float	Default value for the OUT parameter, if a sensor or sensor electronic fault is detected. The unit of this parameter is the same like the OUT one
35	ALARM_HYS	Float	Hysteresis
36	NULL_PARAM	--	
37	HI_HI_LIM	Float	Value for upper limit of alarms
38	NULL_PARAM	--	
39	HI_LIM	Float	Value for upper limit of warnings
40	NULL_PARAM	--	
41	LO_LIM	Float	Value for lower limit of warnings
42	NULL_PARAM	--	
43	LO_LO_LIM	Float	Value for lower limit of alarms
44	NULL_PARAM	--	

45	NULL_PARAM	--	
46	HI_HI_ALM	Record	
	Unacknowledged	Unsigned8	State of the upper limit of alarms.
	Alarm_State	Unsigned8	
	Time_Stamp	TimeValue	
	Subcode	Unsigned16	
	Value	Float	
47	HI_ALM	Record	State of the upper limit of warnings
	Unacknowledged	Unsigned8	
	Alarm_State	Unsigned8	
	Time_Stamp	TimeValue	
	Subcode	Unsigned16	
	Value	Float	
48	LO_ALM	Record	State of the lower limit of warnings
	Unacknowledged	Unsigned8	
	Alarm_State	Unsigned8	
	Time_Stamp	TimeValue	
	Subcode	Unsigned16	
	Value	Float	
49	LO_LO_ALM	Record	State of the lower limit of alarms
	Unacknowledged	Unsigned8	
	Alarm_State	Unsigned8	
	Time_Stamp	TimeValue	
	Subcode	Unsigned16	
	Value	Float	
50	SIMULATE	Record	For commissioning and test purposes the input value from the Transducer Block into the Analog Input Function Block AI-FB can be modified. That means that the Transducer and AI-FB will be disconnected
	Simulate_Status	Unsigned8	
	Simulate_Value	Float	
	Simulate_Enable	Unsigned8	
51	OUT_UNIT_TEXT	OctetString(16)	

7.2 IDENT NUMBER

Profibus devices have unique ID numbers. An ID allows devices connected to the bus to be identified. The Ident Number of the Series 4000-Profibus PA is: 0FAB (hex). The Ident Number is also stored in the GSD File.

7.3 GSD FILES

GSD (General Station Description) Files are needed to configure a profibus network. GSD files containing general information and device-specific capabilities about the transmitter. The PLC or a configuration tool reads the device identification, adjustable parameters, data type and the limiting values of the transmitter from this GSD file. The GSD file is usable for all Profibus master that are compatible to the standard and configured for the floating point standard **IEEE754**.
The GSD files are available at: **www.klay.nl** under section downloads.

7.4 ENGINEERING UNITS

The following engineering units are supported by the Series 4000 Profibus PA.

Index	Unit	Description
1132	MPa	megapascal
1133	kPa	kilopascal
1137	bar	bar
1138	mbar	millibar
1140	atm	atmosphere
1145	kgf/cm^2	kilogram-force per square centimeter
1147	inH_2O (inWC)(4°C)	inch of water at 4 °C
1150	mmH_2O (mmWC)(4°C)	millimeter of water at 4 °C
1158	mmHg (0°C)	millimeter of mercury
1001	° C	Celsius
1002	° F	Fahrenheit

Additional units can be configured in the Analog Input Block. This is explained step by step by an example:

- The Span is set to 1.000 bar in program point P102. (0 till 1.000 bar)
- In the Analog Input Block index value 27 is automatically filled with calibrated span of 1.000 bar.
- In the Analog Input Block index value 28 must be filled in for scaling from bar to torr:
- **OUT_SCALE** = 750.06375541921 (1 bar = 750.06375541921 torr)
- **EU_at_100%** = 750.06375541921 and **EU_at_0%** = 0
- **Units_Index** = 1139 (Corresponding Engineering unit for torr)
- **Decimal_Point** = 2
- The converted output is available on index value 26 (OUT) in the Analog Input Block.

⚠ **When the Engineering Unit is changed on the transmitter with Programming point P104 or P109, the conversion in the Analog Input Block will be invalid and must re-calculated and configured as described above. The same applies when the SPAN is changed.**

Configuring the transmitter local and remote simultaneously will cause transmission errors and must be prevented.

7.5 PROFIBUS ADDRESS

The Series 4000-PROFIBUS PA is standard configured at address **126** (Unconfigured Device). This address is used for configuration and commissioning purpose only. The address can be changed with Program point P113 or a Profibus Master device (Only Class 2).

8 ROTATABLE DISPLAY

The display from Series 4000 is fully rotatable. To rotate the display, place a small screw driver into the recess on top of the display. Turn it by hand by moving the screw driver into the desired direction, use the other hand to guide this movement to avoid any damages. The display can be turned both left and right.

9. SPECIFICATIONS

Manufacturer		Klay Instruments B.V.		
Instrument		Series 4000 and Series 4000-SAN		
Output		Profibus PA - Slave Profile V3.02 Floating point IEEE754		
Power Supply		12 - 30 Vdc		
Transmission speed		31.25 kb/sec		
Current consumption		13 mA ± 1 mA		
Fault current		13 mA ± 1 mA		
Accuracy		0,075% - (Turn down 10:1) 0,1% - (Turn down 10:1 … 20:1)		
Ranges [1]	**Code**	**Adjustable span ranges**		**Max. overpressure**
Series 4000	20 30 40	0-0,1 bar 0-0,5 bar 0-5 bar	0-1,2 bar 0-10 bar 0-100 bar	6,4 bar 50 bar 200 bar
Series 4000-SAN	20 30 40	0-0,05 bar 0-0,5 bar 0-5 bar	0-1,2 bar 0-10 bar 0-100 bar	10 bar 50 bar 200 bar
Series 4000 [2]		High Pressure	Option G83	> 600 bar
Process Temperature Series 4000-SAN [3] Series 4000		-20°C to +100°C (-4°F to 212°F) -20°C to +80°C (-4°F to 176°F) (Optional 100°C)		
Ambient Temperature Series 4000/4000-SAN		-20°C to +70°C (-4°F to 158°F)		
Temperature effect		0,015 %/K		
Damping		0,00 seconds to 25,00 seconds Standard: 0,00 seconds.		
Protection Grade		IP66		
Material	Housing *"wetted"* parts	AISI 304 (Optional AISI 316) AISI 316 L (Other materials on request)		

1: For vacuum applications and compound ranges in combination with higher process temperatures a special oil filling must be applied (Option G26).
2: For pressures higher than order code 40, Contact Klay Instruments for information.
3: For higher temperatures use other kind of pressure transmitters. Contact Klay Instruments for information.

10. PRECAUTIONS AND WARNINGS

- Check if the specifications of the transmitter meet the needs of the process conditions

- When the Series 4000-SAN is used as a level transmitter, be aware of the place where the transmitter is mounted. Here are some suggestions:
  1. DO NOT mount a level transmitter in- or near filling or discharging pipes.
  2. In case of automatic cleaning systems or hand cleaning: never point the water jets on the diaphragm, take necessary steps to avoid this. Guarantee will not be granted.

- When the Series 4000 is used as a pressure transmitter, be aware of the following points:
  1. Rapid closing valves in combination with high flow velocity will cause water hammer(spikes) and can destroy the transmitter. DO NOT mount a transmitter near such valves, always a few pipe bends away up or down stream (avoid suction).
  2. Install a pressure transmitter a few pipe bends away from pumps, as well on the suction or pressure side of the pump

- WELDING INFORMATION:
  When using the Series 4000 or 4000-SAN code "W" the welding information on page 4 must be followed exactly. This is very important to prevent distortion of the weld-on nipples. It also prevents the screw thread from the Series 4000-SAN (M56 x 1,25) from being deformed.

- The diaphragm of the transmitter is protected with a special protection cap. Protect the diaphragm until installation takes place, to prevent damaging of the diaphragm.

- Configuring the transmitter local and remote simultaneously will cause transmission errors and must be prevented.

- As soon as the wiring is brought inside through the cable gland and connected to the terminal board, make sure the cable gland is tightly fixed, so that moisture cannot enter into the electronic housing.

- Avoid high pressure water-jets pointed at the venting.

- If the ambient conditions are very wet, we advise to use a venting through the cable. A special vented cable can be connected on request. (The normal venting will be removed) In that case the transmitter is IP68.

- The covers ① and ③ must be fully engaged, so that moisture cannot ingress into the electronic housing.

- WARRANTY: The warranty is 1 year from delivery date.
  Klay Instruments B.V. does not accept liability for consequential damage of any kind due to use or misuse of the Series 4000. Warranty will be given, to be decided by the manufacturer. Transmitter must be shipped prepaid to the factory on manufacturers authorization.

- NOTE: Klay Instruments B.V. reserves the right to change its specifications at any time, without notice. Klay Instruments B.V. is not an expert in the customers process (technical field) and therefore does not warrant the suitability of its product for the application selected by the customer.

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